Solution outline to Homework 7

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1 Problem 7.3

There are three materials 1, 2, 3. The volume variables associated with them are x_1, x_2, x_3 . Constraints are as follows

The cost function is given as

Maximize $1000x_1 + 1200x_2 + 12000x_3$

2 Problem 7.8

I had already sent portions of the formulation in my email. Points denote the set of all points where each point is a 2-tuple (x_i, y_i) . Constraints of the linear program are as follows

 $\begin{array}{rcl} \forall i \in Points \\ e_i & \geq & ax_i + by_i - c \\ e_i & \geq & -(ax_i + by_i - c) \\ \forall i \in Points \\ M \geq e_i \end{array}$

The cost function is given by

Minimize M

3 Problem 7.11

Dual LP

 Solution of primal LP (Solve graphically) is $x = \frac{4}{5}$, $y = \frac{7}{5}$. Similarly solution of dual LP is $\lambda = \frac{2}{5}$, $\nu = \frac{1}{5}$. By LP duality verify that at these points the cost functions of primal and dual LP computes to the same value of 2.2.

4 Problem 7.17

(a) Max flow : 4+2+2+3 = 11, Min Cut : {s,a,b}, {c,d,t}

(b)Vertices reachable from S are $\{A,B\}$ while vertices from T are $\{C\}$

(c)Bottleneck Edge Identification: {AC,BC}

(d)The example is shown in Figure 1

(e)Algorithm outline for Bottleneck Edge Idenitification: Generate the residual graph after the ford-fulkerson



Figure 1: Counterexample for Shortest Path Tree

algorithm is run. Consider each edge (source, sink) in the residual graph where source, sink $\in V$. If s is reachable from source and t is reachable from sink then (source, sink) is a bottleneck edge. Reachability property proves the correctness of the algorithm since if s and t are not reachable from source and sink it is not possible to augment more flow on the path from s to t and then increasing the capacity of edge (source, sink) doesn't increase the maximum flow.

5 Problem 7.25

(a)We define flow variables f_{ij} on each edge $(i, j) \in E$ of the graph G=(V,E). Based on the that maximum flow from S to T can be written as a linear program as follows

Maximize
$$f_{sa} + f_{sb}$$

Subject to
 $f_{sa} \le 1$
 $f_{sb} \le 3$
 $f_{ab} \le 1$
 $f_{at} \le 2$
 $f_{bt} \le 1$
 $f_{sa} = f_{ab} + f_{at}$
 $f_{sb} + f_{ab} = f_{bt}$
 $f_{sa}, f_{sb}, f_{ab}, f_{at}, f_{bt} \ge 0$

(b)Dual of the linear program: We have dual variables λ_{ij} associated with each edge $(i, j) \in E$ and ν_i associated with each vertex $i \in V$ in the graph G=(V,E).

Minimize
$$\lambda_{sa} + 3\lambda_{sb} + \lambda_{ab} + 2\lambda_{at} + \lambda_{bt}$$

Subject to
 $\lambda_{sa} + \nu_a \ge 1$
 $\lambda_{sb} + \nu_b \ge 1$
 $\lambda_{ab} - \nu_a + \nu_b \ge 0$
 $\lambda_{at} - \nu_a \ge 0$
 $\lambda_{bt} - \nu_b \ge 0$
 $\lambda_{sa}, \lambda_{sb}, \lambda_{ab}, \lambda_{at}, \lambda_{bt} \ge 0$
 ν_a, ν_b Unrestricted

(c)General dual formulation can be written as

$$\operatorname{Minimize} \sum_{\forall e \in E} c_e y_e \tag{1}$$

$$y_{ij} - x_i + x_j \ge 0 \forall (i,j) \in E, i, j \notin \{s,t\}$$

$$(3)$$

$$y_{si} + x_i \ge 1 \forall (s,i) \in E \tag{4}$$

$$y_{jt} - x_j \ge 0 \forall (j, t) \in E \tag{5}$$

 $y_{ij} \ge 0 \forall (i,j) \in E \tag{6}$

(7)

(d)Summing up constraints 1-3 we can obtain that

$$\sum_{\forall (i,j) \in E} y_{ij} \ge 1$$

(e) x_u is the potential defined on the vertices. y_e represents if the specified edge is on a cut. Given a graph G=(V,E), for any cut $V = V1 \cup V2$. For an edge (u, v) if $u \in V1$ and $v \in V2$ then $y_{(u,v)} = 1$ othewise $y_{(u,v)}$ is 0. For all nodes $u \in V1$ set x_u as 1 and for all nodes in $u \in V2$ set x_u as 0. The assignment satisfies the constraints given and the cost function $\sum_{\forall e \in E} c_e y_e$ exactly sums up the capacities of edges in a cut.

6 Problem 7.31

(a)2000 augmenting paths can be found out each sending a single unit of flow in this particular graph. (b)We define the capacity of a s-t path as the smallest capacity of its constituent edges. We define a variable *cap* on each vertex.

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procedure IdentifyFattestPath(G,c_e,s)

Input: Graph G=(V,E), c_e capacity of edge e

source vertex s

Output: Fattest s-t path

for all vertices v \in V:

cap(v) = \infty

prev(v) = nil

H = makequeue(V) (using cap values as keys)

while H is not empty:
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(c)Using the duality of Maximum flow problem we know that there is a min-cut associated with the maximum flow. Now min-cut divides the vertices V into two sets V1 and V2. Each edge e in the cut must be an edge of some s - t path in the graph and the flow associated with this path is capacity of the edge c_e . Therefore the maximum flow must be the sum of the capacity of edges corresponding to min-cut edges e. Since edges in a min-cut are bounded by |E|, therefore maximum flow can be decomposed into at most |E| paths. (d)Since F is the sum of the flow over at most |E| paths, therefore each flow augmentation decreases the maximum flow bound by $\frac{1}{|E|}$. After k iteration the maximum flow bound is given by

$$F(1-\frac{1}{|E|})^k$$

Following discussion in greedy set cover algorithm, k is given by $O(|E| \log F)$.